

# International Study Visit, Germany 27-31 Jan 2020



***Bilkent University***

***Sedat OZER***

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International Study Visits of TARAL to EU Key Players

# Dept. of Computer Engineering, Bilkent University

- At the heart of the capital city: Ankara
  - Have access to many robotics companies, research hospitals and agencies in the region
- Our students are among the top in Turkey
  - Bilkent focuses on academic excellence
- Have multiple faculty researching on:
  - AI & Machine Learning
  - Robot Sensing & Computer Vision
  - Data Analysis fields

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# Dr. Sedat Ozer - Education and Research Experience

## EDUCATION

- M.Sc. from Univ. of Massachusetts, MA, USA
- Ph.D. from Rutgers University, NJ, USA



## RESEARCH

- Univ. of Central Florida (UCF), FL, USA between 2018 – 2019
  - Center for Research in **Computer Vision** (CRCV)
- Massachusetts Institute of Technology (MIT) between 2015 - 2017
  - **Distributed Robotics Lab**, CSAIL
- Univ. of Virginia, VA, USA, between 2013 - 2015
  - Virginia Image and **Video Analysis** (VIVA) lab



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# About Me and My Research Team

- Recently joined the department and my team is growing:
  - By the end of this summer, will have 6 PhD students
  - 2 M.Sc. Students & 6 undergraduate students
  - Co-advising multiple M.Sc. and PhD students in various institutions
- My expertise is in:
  - AI Algorithm Design
  - Machine Learning Theory
  - Data Analysis & Visualization
  - Robot Sensing & Computer Vision

## Collaborating Institutions



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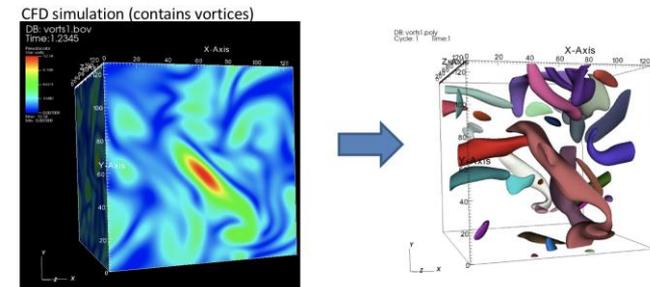
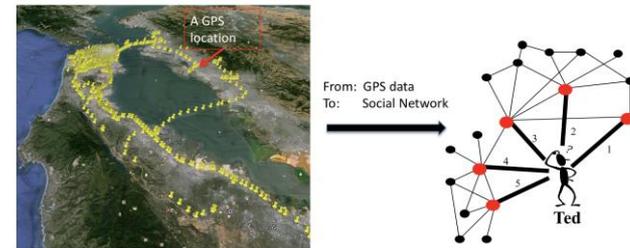
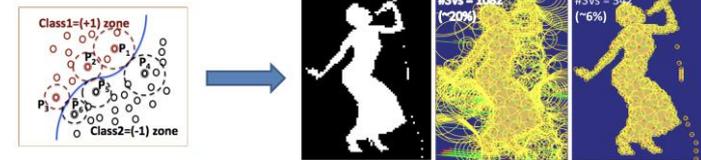
# R&D

- I have worked on many projects funded by local agencies in USA.
- Currently, I am the PI on a TUBITAK 2232 project at Bilkent University
  - focuses on designing reliable object detection algorithms for autonomous systems

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# Sample Projects

- Interpretable Machine Learning Algorithm Design, [IEEE TIP, 2019]
- Social Network extraction from streaming GPS data, [ICML 2017]
- Activity Detection in Scientific Datasets [IEEE TVCG 2013]
  - Object segmentation, tracking, and activity modelling,



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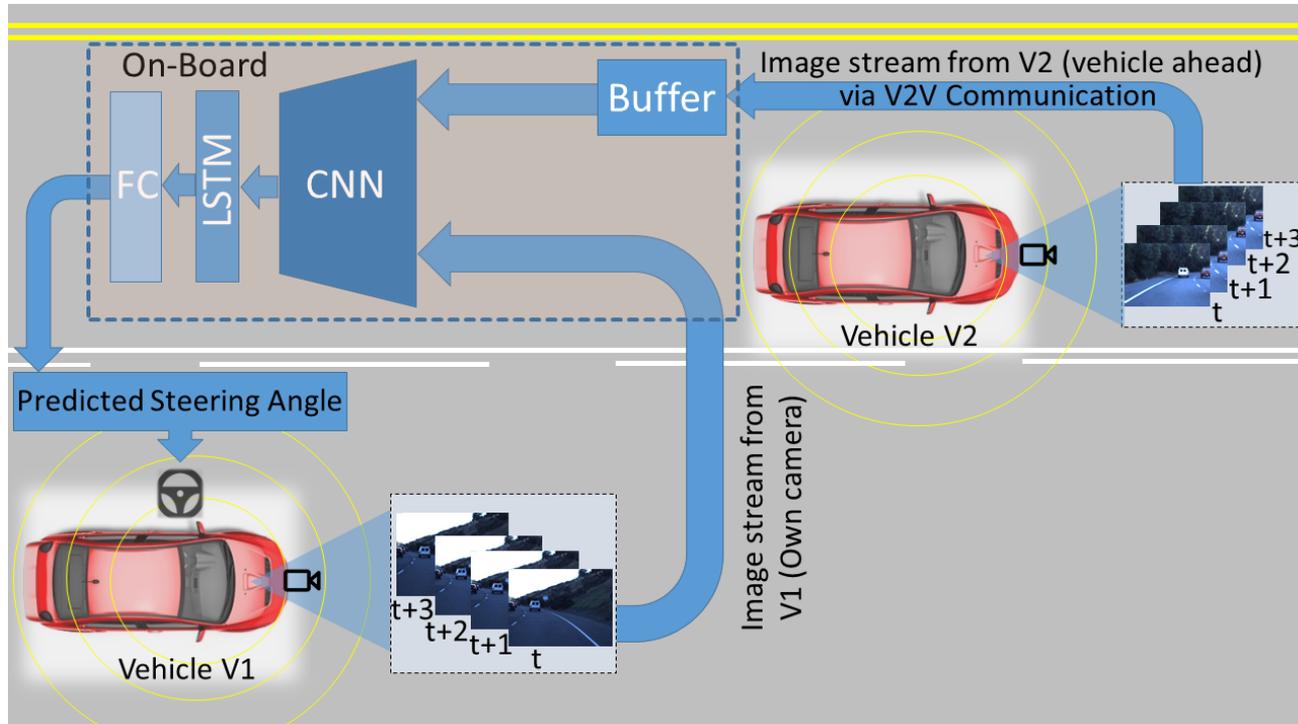
# Video Data (Analysis) in Computer Vision



- **Object Detection**
- **Object Tracking**
- **Anomaly Detection**
- **Activity Detection**

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# Controlling Steering Angle for a Self-driving Car in Cooperative Environments



Published at IEEE Intelligent Vehicles Symposium 2019

First vision paper using V2V communication

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# Ideas: Multimodal Data Fusion for Robot Sensing

## Horizon 2020:

- **ICT-46-2020: Robotics in Application Areas and Coordination & Support**
  - (AI and Cognition)
- **ICT-47-2020: Research and Innovation boosting promising robotics applications**
  - **Application and integration of non-visual sensing novel for service robotics**

(Multi-modal fusion)

- Chemical properties
- Sound
- Physical properties
  - Can be measured by cameras, etc.

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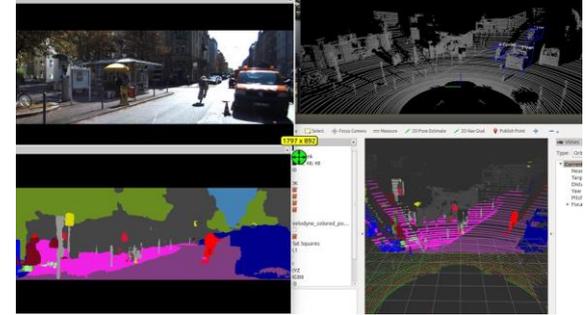
# Ideas: Designing Explainable & Interpretable AI Algorithms

- Deep Reinforcement Learning for Enhancing **Robot Cognition**
- Deep Reinforcement Learning for **Cognitive Mechatronics**:
- GANs for **Robot Cognition**
- Learning to learn for **Robot Cognition**

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# Ideas: AI for Autonomous Systems

- Object detection
- Tracking and
- Scene parsing



Multi-Modal Fusion

- RGB Image
- IR image
- LIDAR
- Sound

New Algorithm Design for AI-based Cognition for:

- For Autonomous Robots
- For Robot Navigation

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# Consortium

I bring:

- **expertise and experience in AI algorithm design (AI, data fusion, data analysis, robot sensing / vision, visualization)** for consortium to use in various robotics applications
- **an international support** not only from Turkey but also from US (if needed)
- **connections to Turkish market:** Turkish Companies / Researchers
- **support with multiple PhD** and / or M.Sc. Students
- I am open to new collaborations in EU & looking for challenging problems to tackle with.

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