

A novel Adaptive Cybersecurity Framework for the Internet-of-Vehicles

# **Project Overview**

**Presenters:** 

Dr. Dimitrios Tzovaras, CERTH/ITI Dr. Votis Konstantinos, CERTH/ITI



#### Outline

- Project Identity Card
- The Consortium
- Rationale & Motivation
- Project Vision & Objectives
- Project Pilots
- Work plan and GANTT







Title: A <u>novel Adaptive Cybersecurity Framework for the Internet-of-</u> <u>Ve</u>hicles

H2020 Call: H2020-SU-ICT-01-2018 (Dynamic Countering of cyber-attacks)

Funding Instrument: **IA** (Innovation Action)

Duration: **36 months** 

Starting Date: 1 May 2019

EU Contribution and Total Costs: 4.997.125,00 €

Partners: 13 partners

Country Coverage: 7 countries

Greece, Italy, Switzerland, Germany, Sweden, Spain and Israel

## The Consortium



No.	Participant organisation name	Country	Type of Organisation
1 (Coord.)	Centre for Research and Technology Hellas [CERTH]	GR	Research
2	University of Geneva [UniGe]	СН	University
3	NAVYA SAS [NAVYA]	FR	SME
4	Research Institutes of Sweden [RISE]	SE	Research
5	ARGUS Cyber Security [ARGUS]	ISA	Industry
6	ESCRYPT GmbH – Embedded Security [ESCRYPT]	DE	Industry
7	ICT Legal Consulting [ICTLC]	IT	SME
8	ATHINA-EREVNITIKO KENTRO KAINOTOMIAS STIS TECHNOLOGIES TIS PLIROFORIAS, TON EPIKOINONION KAI TIS GNOSIS <b>[ISI]</b>	GR	Research
9	SMART ENGINEERING & MANAGEMENT SOLUTIONS IKE [SEEMS]	GR	SME
10	Technical University of Munich [TUM]	DE	University
11	Transports Publics Genevois [TPG]	СН	Public
12	KENOTOM Private Company [KENOTOM]	GR	SME
13	HOP Ubiquitous [HOPU]	ES	SME

# Challenges by the SU-ICT-01-2018 Call



- The prevention of and the protection against attacks that target modern ICT components and emerging technologies (e.g. IoT) remains a difficult task.
- The increase of encrypted flows over the Internet should lead to adopt new techniques for detection of suspicious cyber activities and traffic patterns, and for classification of flows, while keeping privacy and confidentiality.
- Innovative, integrated and holistic approaches in order to minimize attack surfaces through appropriate configuration of system elements, trusted and verifiable computation systems and environments, secure runtime environments, as well as assurance, advanced verification tools and secureby-design methods





Today's vehicles are increasingly "connected"; there is wireless data exchange with servers, infrastructure and other vehicles.

<u>**There is not**</u> a dedicated scientific field studying the protection of Connected and Autonomous Vehicles (CAVs) against cyber-attacks and thus, the respective research endeavours are limited.

Over <u>85% of all new cars are already classed as connected</u>, and by 2025 there will be over 470 million connected vehicles on the roads in Europe, the USA and China alone.

Attacks on automobile systems are <u>expected to increase rapidly</u> in the following years due to the rapid increase in connected automobile hardware & software without foundational cybersecurity principles.



## nIoVe Motivation



Heterogeneous network architecture of IoV ecosystem includes many types of vehicular communications:

- Vehicle-to-Vehicle (V2V)
- Vehicle-to-Infrastructure (V2I)
- Vehicle-to-Network (V2N)
- Vehicle-to-Pedestrian (V2P), etc.







Overview of nIoVe Scope and Identity				
Application field:	Cybersecurity in connected and autonomous vehicles	Mode of transport:	Connected and autonomous vehicles of different types (e.g. mini-buses, cars)	
Targeted areas:	Smart Cities; Urban Environments Vehicles setup: Fleets of CAVs			
Target users:	All; Of specific interest: people with disabilities; OEMs; Tier suppliers; Cybersecurity companies			
Technologies employed:	Anomaly detection, blockchain, data & visual analytics; V2V, V2I, V2N communication, IoT	Services to be provided & improvements:	Risk assessment, Response and Recovery toolkits, hypothesis testing, virtualized honeypots; threat info repository	
<u>Ultimate goal:</u>	<b>To develop, deploy and validate <u>a</u> suitable to offer security assessment smart cities infrastructure, etc.) and</b>	<u>holistic and multi-la</u> t in IoV ecosystem (c OEMs.	ayered Cybersecurity Framework connected and autonomous vehicles,	

### nIoVe Vision



#### nloVe aims to:

- identify the risks associated with connected of vehicles and IoV networks
- recognise and evaluate suspicious threat patterns with the use of advanced Machine Learning (ML) algorithms
- enable appropriate coordinated mitigation actions in order to address CAVs safety/security and ensure proper CAVs performance and data management
- offer (near) real time detection of anomalies, as well as response against evolving complex cyber-attack and successful recovery
- open up the cybersecurity 'blackbox' to connected and autonomous vehicles

# nloVe Objectives (1/4)



	Objective	WPs	KPIs
Obj.1	To deliver a multi-layered cybersecurity solution for the IoV ecosystem in order to provide protection against wider area of attacks	WP3- WP7	<ul> <li>Meet at least 85% of users requirements concerning cybersecurity and privacy objectives (identified during the user requirement analysis)</li> <li>Improvement by up to 100% of the usability of current services and solutions for a given security level</li> <li>Toolkit functionalities for cyber-risk reduction concerning privacy, data and infrastructures of the IoV ecosystem</li> </ul>
Obj.2	To research and develop a Machine Learning (ML)- Driven Threat Analysis and Situational Awareness Platform for the IoV	WP3	<ul> <li>Detection time for complex cyber-attacks : 24 hours</li> <li>Detection effectiveness: 99% accuracy of known threats; 90% for zero-day exploits; Improved cybersecurity in IoV ecosystem (overall): 99.5% of cyber-threats/ potential attacks are identified</li> <li>Automation metrics of the nIoVe: (a) Increased averaged automation level: 4.5 to 5 out of 5 (or +20%) compared to existing cutting-edge solutions (measured at task/ function level); (b) Increased automation effectiveness: 3,5-4,5 / 5 or detection rate: 10% improvement; +30% reduction of false alarms and unidentified threats (FPR, FNR, TPR, TNR )</li> <li>Number of Major or Small Security Incidents: Continuous comparison and evaluation of the current situation based on historical data for potential incidents</li> </ul>





	Objective	WPs	KPIs
Obj.3	To introduce advanced Visualization and Big Data techniques required for the detection of complex cyber- attacks	WP4	<ul> <li>Wide understanding of security services and analytics: &gt;75% of CAVs manufacturers comprehend the 100% of the nloVe functionality they are interested in (in respect of security status, potential threats, risk notifications, etc.).</li> </ul>
Obj.4	To introduce a coordinated cyber Incident Smart Response System for CAVs at national & European level	WP5	<ul> <li>Amount of Time to Resolve an Incident: 20% reduction the time it took to resolve a cyberattack incident, from the moment it was first noticed until the final wrap-up meeting or report</li> <li>Uptime (or Downtime) During an Incident: 20% reduction the cost of downtime during a security incident keeping backup files through recovery toolkit</li> <li>Appropriate Management of End-user Impact: Maximum collection and storage of data during the attack time and 100% recovery of saved data</li> <li>Demonstrate effective response to cyber and hybrid security and privacy threats/ attacks of &gt; 98.5%</li> </ul>





	Objective	WPs	KPIs
Obj.5	To maximise trust between CAVs and infrastructure components through trust management and identification platform	WP5	<ul> <li>Clear accountability (in the sense that it can be automated) for &gt;85% of the interactions/ communications performed in integrated IoV settings (defining who is accountable for what)</li> </ul>
Obj.6	To establish and operate a continuously updated and shared Threat Intelligence Repository for CAVs cyber threats to support OEMs and Tier suppliers	WP6	<ul> <li>Threat intelligence: aggregation of threat intelligence from all CAVs pilots, sensitive data &amp; user accountability</li> <li>Reported Incidents of End-user Impact: Continuous information sharing between CAVs manufacturers, ECUs providers, automotive industries, CSIRTs etc. for threats, attacks and recovery/response services</li> </ul>

# nloVe Objectives (4/4)



	Objective	WPs	KPIs
Obj.7	To support of secure-by- design production lifecycle for all vehicle communications	WP7	<ul> <li>Operating capacity of the simulation infrastructure: Support secure-by-design new product development of CAVs; execution of the certification process for the CAVs</li> <li>Meeting Regulatory Requirements: Training and compliance the CAVs manufacturers and providers regarding regulations and rules for the secure and safe development of new hardware and software components.</li> </ul>
Obj.8	To provide cybersecurity solutions to cover execution environments (Smart Cities' infrastructure elements) including all mechanisms (authentication/access control mechanisms, etc.)	WP7	• Demonstration of the system prototype in an execution environment (TRL6)
Obj.9	To validate the nIoVe architecture capabilities in proof-of-concept Use Cases	WP7	<ul> <li>Number of Demonstrations: Hybrid execution environment for use case 1, simulated environment for use case 2 and real-world conditions (Geneva City) for use case 3</li> </ul>

#### nloVe Concept





Kick-off Meeting, Thessaloniki, Greece, 20-21 May 2019

### nIoVe Architecture

nIoVe Technical Architecture is divided *into 4 layers*:

- Bottom layer: Internet-of-Vehicles Infrastructure
- Second Layer: Secure Communication Layer
- Main Layer: SIEM (Security Information and Event Management) Platform for IoV
- Topmost layer: Users and Beneficiaries



## nIoVe Pilot Site #1

Category: Hybrid execution environment

#### Scenarios to be tested:

- Minor issues: blinking leds, false speedometer and fuel readings, infotainment and telematics
- Critical issues: attack on GPS position and navigation, cyber-ransom
- **Privacy**: collect information from the vehicle and/or from its passengers
- Safety: damage engine, accelerate vehicle, disable brakes, take control of steering wheels, emergency breaking (especially when operating in high Levels of Automation)
- Apply nIoVe active and passive responses to CAV
- Run diagnostics and software updates during operation

End Users: Automated Vehicles Manufactures; IoT devices providers; Cybersecurity experts





# nIoVe Pilot Site #2



**Category:** Simulated Environment

#### Scenarios to be tested:

- **Minor issues**: blinking leds, false readings (e.g. speedometer, fuel readings, engine status), the operation of after-market products (mostly related to infotainment and telematics)
- Critical issues: GPS position and guided navigation, lock the car by distance, false manoeuvre detection, false Smart-City readings (e.g. traffic light status, traffic alerts)
- Car Theft: Unlock doors, open windows, bypass immobilizer
- Privacy: Eavesdrop, GPS location tracking, access to personal data, collect information from the vehicle
- **Safety**: damage engine, accelerate, disable brakes, take control of steering wheels, emergency breaks
- **Emergency**: attacks to the eCall and emergency services
- Drive analysis

End Users: CAV manufactures; ECUs providers; Automotive Industries; CSIRTs



# nIoVe Pilot Site #3



Category: Real smart city execution environment

#### Scenarios to be tested:

- Smart City infrastructure: sensors return incorrect readings;
- **Transport Information System**: incorrect transport information readings, like incorrect occupancy (for buses, trains, metro, tram & trolleys), destination (for public transportation means), expected arrival time, transportation availability;
- CAVs: incorrect GPS position, guided navigation, drive analysis;
- Privacy: Citizens eavesdrop, unauthorized access to passenger's data

**End Users:** All, Passengers, Citizens, Pedestrians, Drivers





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